

## **AMENDMENT TO THE CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application:

### **Listing of Claims:**

1. (currently amended) An ultrasonic flow sensor, ~~including comprising~~
  - at least one ultrasonic transducer (~~A, B~~) for transmitting and receiving ultrasonic signals (~~A0, B0~~), and
  - a receiver unit (4) ~~that is connected to the ultrasonic transducer (A, B) and that~~ detects a predetermined event (N) of the ultrasonic signal (~~A0, B0~~) as the a reception time ( $t_0$ ),wherein the receiver unit (4) ~~is embodied in such a way that it~~ determines the a time ( $t_1$ ) of a value ( ~~$Amp_{max}$ ,  $T_s$~~ ) characteristic of the ultrasonic signal (~~A0, B0~~) and ~~determines the~~ as well as a time shift ( $\Delta t$ ) of the time ( $t_1$ ) in relation relative to the reception time ( $t_0$ ) and  
uses the time shift ( $\Delta t$ ) to determine a correct time value for the reception time ( $t_0$ ).
2. (currently amended) The ultrasonic flow sensor as recited in claim 1, wherein the receiver unit (4) determines a maximum amplitude ( $Amp_{max}$ ) of the ultrasonic signal (~~A0, B0~~) as a characteristic value.
3. (currently amended) The ultrasonic flow sensor as recited in claim 1, wherein the receiver unit (4) determines the a chronological position ( $T_s$ ) of the focal point of either the ultrasonic signal (~~A0, B0~~) or its envelope curve (6) as the characteristic value.
4. (currently amended) The ultrasonic flow sensor as recited in claim 1, wherein the receiver unit (4) includes a comparator (10) whose input is supplied with a transducer output signal (5) and a reference signal (SW), and the receiver unit (4) determines a piece of information about the time ( $t_1$ ) of the characteristic value ( ~~$Amp_{max}$ ,  $T_s$~~ ) from the output signal of the comparator (10).
5. (currently amended) The ultrasonic flow sensor as recited in claim 4,

wherein the reference signal supplied to the comparator (10) is a threshold (SW) not equal to zero and the output signal of the comparator (10) is a pulse width modulated signal (K1) from which the time ( $t_1$ ) of the characteristic value ( $Amp_{max}$ ,  $T_s$ ) is determined.

6. (previously presented) The ultrasonic flow sensor as recited in claim 1, wherein the reception time ( $t_0$ ) is corrected as a function of the time shift ( $\Delta t$ ).

7. (currently amended) A method for detection of an ultrasonic signal (A0, B0) in an ultrasonic transducer (~~A, B~~) by means of a receiver unit (4), which detects a predetermined event (N) of the ultrasonic signal (~~A0, B0~~) as a reception time ( $t_0$ ), wherein the receiver unit (4) determines the a time ( $t_1$ ) of a value ( $Amp_{max}$ ,  $T_s$ ) characteristic of the ultrasonic signal (~~A0, B0~~) and determines the a time shift ( $\Delta t$ ) of the time ( $t_1$ ) in relation to the reception time ( $t_0$ ) and uses the time shift ( $\Delta t$ ) to determine a correct time value for the reception time ( $t_0$ ).

8. (currently amended) The method as recited in claim 7, wherein the receiver unit (4) determines a maximum amplitude ( $Amp_{max}$ ) of the ultrasonic signal (~~A0, B0~~) as a characteristic value.

9. (currently amended) The method as recited in claim 7, wherein the receiver unit (4) determines the a chronological position of the a focal point of the ultrasonic signal (~~A0, B0~~) or its envelope curve (6) as a characteristic value.